ON THE LIFTS OF SEMI-RIEMANNIAN METRICS

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Abstract

In this paper, we extend Sasaki metric for tangent bundle of a Riemannian manifold and Sasaki-Mok metric for the frame bundle of a Riemannian manifold [1] to the case of a semi-Riemannian vector bundle over a semi-Riemannian manifold. In fact, if E is a semi-Riemannian vector bundle over a semi-Riemannian manifold M, then by using an arbitrary (linear) connection on E, we can make E, as a manifold, into a semi-Riemannian manifold. When the metric of the vector bundle E is parallel with respect to the chosen connection, we compute the Levi-Civita connection of E, its geodesics, and its curvature tensors. We also show that the sphere and pseudo-sphere bundles of E are non-degenerate submanifolds of E, and we shall compute their second fundamental forms. We shall also prove some results on the metric of E.

Preliminaries

Let (V, ...) be a finite dimensional inner product space. For each $v \in V$, sgn(v) is defined as follows

$$sgn(v) = \begin{cases} +1 & v.v > 0 \\ 0 & v.v = 0 \\ -1 & v.v < 0 \end{cases}$$

There exist bases like $\{e_1, ..., e_n\}$ in V such that e_i . $e_j = \pm \delta_{ij}$ [4]. We call them orthonormal bases. Vector spaces associated with V such as V^* , $L(V), \otimes^r V$, and $\wedge^r V$ can be made into inner product spaces in a natural way. If the inner product is not positive or negative definite, the restriction of it to a subspace is not in general an inner product. In fact, if W is a subspace of V, and W^{\perp} is its orthogonal, the restriction of the inner product to W makes it an inner product space if and only if $W \cap W^{\perp} = \{0\}$ (or equivalently $V = W \oplus W^{\perp}$). If

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this is the case we call W a non-degenerate subspace.

Let $\diamondsuit(V)$ denote the space of all antisymmetric linear maps on V, the linear map $\wedge^2 V \to \diamondsuit(V)$, which sends $u \wedge v$ to the map $x \mapsto (vx)u - (ux)v$, is an isomorphism of inner product spaces. We shall identify $\wedge^2 V$ and $\diamondsuit(V)$ under this isomorphism.

By manifolds we mean C^{∞} real manifolds. The vector bundle (E, π, M, F) will be denoted by $E \xrightarrow{\pi} M$, and the fiber over $p \in M$ will be denoted by E_p . VE will denote the vertical bundle of E. It is well known that VE is a subbundle of TE [9]. For $\xi, \eta \in E$ with

$$\pi(\xi) = \pi(\eta)$$
 we set $I_{\xi} \eta = \frac{d}{dt} I_{t=0} (\xi + t \eta)$. Clearly

 $l\xi\eta\in(vE)_{\xi}$, and it is called the vertical lift of ξ at η .

To each connection ∇ on E there correspond a horizontal subbundle \mathcal{H} (of TE), a connection map k: $TE \to E$, and a parallel system IP [9]. Let $p \in M$, $u \in T_p M$ and $\xi \in E_p$. There exists a unique vector on \mathcal{H}_{ξ} such that its image under $d\pi$ is u. This vector is called the horizontal lift of u at ξ , and it will be

denoted by \overline{u}_{ξ} . The set of all sections of a vector bundle $E \xrightarrow{\pi} M$ will be denoted by ΓE .

Let E be a semi-Riemannian vector bundle over M. The vector bundles E^* (dual of E), L(E), $\otimes^r E$, $\wedge^r E$ (1 $\leq r$) can be made into semi-Riemannian vector bundles in a natural way.

Let M be a semi-Riemannian manifold, a submanifold N of M is called semi-Riemannian submanifold, if for each $p \in N$, T_pN is a non-degenerate subspace of T_pM (of course, if N is connected, then the signature of the inner product on each fiber is constant.). Clearly, in this case, the restriction of the metric of M to N makes it into a semi-Riemannian manifold. Let ∇^M , ∇^N denote the Levi-Civita connection of M and N, respectively, and E be the restriction of TM on N (or equivalently, E be the pull-back of TM over the inclusion map $N \stackrel{i}{\rightarrow} M$). The pull-back of ∇^M , which is a connection on E will be denoted by the same symbol ∇^M . Let $p_1 : E \rightarrow TN$ be the orthogonal projection. Then for each U, $V \in \mathcal{L}$ E

$$\nabla_{U}^{N}V = p_{1}(\nabla_{U}^{M}V)$$

[8]. Let TN^{\perp} be the orthogonal complement of the vector bundle TN in E, and $p_2 \colon E \to TN^{\perp}$ be the orthogonal projection. The map $\pi \colon TN \otimes TN \to TN^{\perp}$ which is defined by $\pi(U,V) = p_2(\nabla_U^M V) = \nabla_U^M V \cdot \nabla_U^N V$ is a symmetric tensor, called second fundamental form of N[8]. Knowing π , we can compute different curvatures of N in terms of the corresponding curvatures of M. Let R^M and R^N denote the curvature tensors of M and N, respectively. Then for each $U, V, W, P \in \mathcal{X}$ N we have

$$< R^{N}(U, V)(W), P > = < R^{M}(U, V)(W), P > + < \pi(U, P), \pi(V, W) > - < \pi(V, P), \pi(U, W) >$$
[8]

Let TN^{\perp} be a line bundle admitting a section Z such that < Z, $Z > = \pm 1$. Then the second fundamental form of N determines a symmetric bilinear form $\overline{\pi}$ on TN as follows:

$$U, V \in \mathcal{X} N$$
 $\overline{\pi}(U, V) = \langle \pi(U, V), Z \rangle$

The bilinear form $\overline{\pi}$ in turn determines a self-adjoint bundle map $S: TN \to TN$

$$U, V \in \mathcal{X} N$$
 $\langle S(U), V \rangle = \overline{\pi}(U, V).$

The bundle map S is called Weingarten map of N (with respect to Z), and can be computed directly as

follows:

$$U \in \mathcal{Y} N$$
 $S(U) = -\nabla_U^M Z$

[8]. Knowing S, the second fundamental form π can be computed as follows:

$$U, V \in \mathcal{X} N$$
 $\pi(U, V) = \langle S(U), V \rangle sgn(Z) Z$

Fundamental Vector Fields of a Vector Bundle

Assume that $\pi: E \to M$ is vector bundle. Let

(x, U) be a chart of M, and $\pi^{-1}(U) \xrightarrow{(\pi, \psi)} U \times IR^k$ be a trivialization of E over U. If $x = (x^1, ..., x^n)$ and $\psi = (\psi^1, ..., \psi^K)$, then

$$(x^1 \circ \pi \dots x^n \circ \pi \cdot \psi^1 \dots \psi^k)$$

is a chart of E whose domain of definition is π^{-1} (U). For each $p \in U$, the restriction of ψ^m (m = 1, 2, ..., k) to

 E_p belongs to E_p^* . Let $\overline{x}^i = x^i$ o π for i = 1, 2, ..., n.

Clearly the vector fields
$$\frac{\partial}{\partial \psi^m}$$
 $(m = 1, 2,..., k)$

generate the vertical subbundle of $TE_{\pi}^{-1}(U)$.

A map $F: E \to E$ is called a strong bundle map if every fiber E_p $(p \in M)$ is invariant under F. If restriction of F to each E_p is linear, it is called a linear strong bundle map.

To each strong bundle map $F: E \rightarrow E$ (not necessarily linear) there corresponds a vertical vector

field of E (a section of vE) which will be denoted by \tilde{F} and is defined by

$$\xi \in E$$
 $\widetilde{F}_{\xi} = I_{\xi} F(\xi)$

 \tilde{F} is smooth, because in local coordinate systems defined above, if $\{\psi_1,..., \psi_k\}$ is dual of $\{\psi^1,..., \psi^k\}$, and F is expressed as $F(\xi) = f^m(\xi)\psi_m$, then f^m 's are smooth $(f^m = \psi^m \circ F)$, and by a direct computation

we have
$$\widetilde{F}_{\xi} = f^m(\xi) \frac{\partial}{\partial w^m}$$
.

For example, if $F = 1_E$, then $\widetilde{1}_E$ is the radial vector field on E. The set of all vertical vector fields on E as well as the set of all strong bundle maps on E, are modules over $C^{\infty}(E)$. From the definition of \widetilde{F} and the local representations of F and \widetilde{F} , we see that the map $F \mapsto \widetilde{F}$ is a linear isomorphism between the above

modules.

Let ∇ be a connection on E throughout the paper, the horizontal subbundle of E (respectively, its connection map, and its parallel system) will be denoted by \mathcal{H} (respectively by k and IP).

To each strong bundle map $A:E\to TM$ (not necessarily linear) there corresponds a horizontal vector field on E (a section of $\mathcal H$) which will be denoted by $\bar A$ and is defined by

$$\xi \in E$$
 $\bar{A}_{\xi} = A(\xi)_{\xi}$

To prove smoothness of \bar{A} , we obtain its local representation. Let

$$v \in T_p M, \xi \in E_p, v = v^i \frac{\partial}{\partial x^i}(p), \xi = \xi^m \psi_m(p),$$

and Γ_{im}^{n} be the Christoffel symbols of ∇ . Then

$$\bar{v}_{\xi} = v^{i} \frac{\partial}{\partial r^{i}} (\xi) - v^{i} \xi^{n} \Gamma_{in}^{m}(p) \frac{\partial}{\partial \psi^{m}} (\xi)$$

[9]. So if A is expressed as $A(\xi) = A^{i}(\xi) \frac{\partial}{\partial x^{i}} (A^{i} = dx^{i} \cap A)$ then

$$\bar{A}_{\xi} = A^{i}(\xi) \frac{\partial}{\partial r^{i}}(\xi) - A^{i}(\xi) \xi^{n} \Gamma_{in}^{m}(p) \frac{\partial}{\partial \psi^{m}}(\xi)$$

For example if E = TM and $A = 1_{TM}$, then $\overline{1_{TM}}$ is the geodesic spray of ∇ . The set of all horizontal vector fields on E as well as the set of all strong bundle maps from E to TM are modules over $C^{\infty}(E)$.

From the definition of \bar{A} and the local representations

of A and \bar{A} it is clear that the map $A \mapsto \bar{A}$ is a linear isomorphism between these modules.

For each $X \in \Gamma$ E (resp. $U \in \chi - M$) $X \circ \pi$ (resp. $\overline{U \circ \pi}$) is called the vertical lift of X (resp. the horizontal lift of U) and it is denoted by IX (resp. \overline{U}).

Proposition 1. Let $F: E \to E$ and $A: E \to TM$ be linear strong bundle maps, and R be the curvature tensor of ∇ then for X, $Y \in \Gamma$ E and U, $V \in \mathcal{X}$ M we have

$$[IX,IY] = 0 \tag{1}$$

$$[\bar{U}, IX] = I \nabla_{U} X \tag{2}$$

$$[\overline{U}, \overline{V}] = [\overline{U}, \overline{V}] - R(\overline{U}, \overline{V})$$
 (3)

$$[IX, \widetilde{F}] = IFoX \tag{4}$$

$$[\overline{U},\widetilde{F}] = \widetilde{\nabla_U} F \tag{5}$$

$$[IX, \overline{A}] = \overline{A \circ X} - \widetilde{\nabla_{A(\cdot)}} X \tag{6}$$

$$[\overline{U}, \overline{A}] = \overline{L_U A} - R(U, \overline{A}(.))(.) \tag{7}$$

In the above relations, R(U, A(.))(.) denotes the bundle map

$$\xi \mapsto R(U \circ \pi(\xi), A(\xi))(\xi)$$
,

A(.) denotes the bundle map $\xi \mapsto A(\xi)$ and $L_U A$: $E \to TM$ is the Lie derivative of A with respect to U given by

$$X \in \Gamma E \quad (L_U A)(X) = [U, A \circ X] - A(\nabla_U X)$$

Proof. For a proof of (1) and (2) see [9]. The relation (3) is followed by the definition of R (see [9]). To prove (5) and (7), note that for each $\xi \in E_p$ there exist some $X \in \Gamma$ E such that $X_p = \xi$ and for each $u \in T_p M$, $\nabla_u X = 0$ [9]. For such $X \in \Gamma$ E, by a computation in local coordinates we obtain

$$[\bar{U}, \tilde{F}]_{\xi} = [\bar{U}, IFoX]_{\xi}$$

$$[\bar{U}, \bar{A}]_{\xi} = [\bar{U}, \bar{A} \circ X]_{\xi}$$

so

$$[\overline{U}, \widetilde{F}]_{\xi} = [\overline{U}, IF \circ X]_{\xi} = (I \nabla_{U}F \circ X)_{\xi} = (I [(\nabla_{U}F)(X) + F (\nabla_{U}X)])_{\xi} = I_{\xi}(\nabla_{U}F)(X_{p}) + I_{\xi}F(\nabla_{U}_{p}X) = I_{\xi}(\nabla_{U}F)(\xi)$$

$$= (\widetilde{\nabla}_{U}F)_{\xi}$$

And for the relation (7) we have

$$[\overline{U}, \overline{A})_{\xi} = [\overline{U}, \overline{A} \circ \overline{X}]_{\xi} = ([\overline{U}, A \circ \overline{X}])_{\xi} - R(\overline{U}, \overline{A}(.))(.))_{\xi}$$

$$= \overline{((L_{U}A)(X)} + \overline{A(\nabla_{U}X)})_{\xi} - I_{\xi}R(U_{p}, A(X_{p}))(\xi)$$

$$= \overline{((L_U A)(\xi))} \xi - I_{\xi} R (U_p, A(\xi))(\xi) = \overline{(L_U A)} \xi - (R(U, A(.))(.)) \xi$$

The assertion (6) is also proved by a computation in a local coordinate. The equality (4) is proved by using the definition of Lie derivative and the flow of IX which is $\varphi_r(\xi) = \xi + tX_{\pi(\xi)}$.

Lift of Semi-Riemannian Metrics

The linear bundle map h from the tangent bundle $TE \xrightarrow{\pi_E} E$ into the vector bundle $E \oplus TM \to M$, defined by $h: \hat{v} \mapsto (k(\hat{v}), d\pi(\hat{v}))$ is an isomorphism over each fiber. Thus $TE \xrightarrow{\pi_E} E$ is the pull-back of $E \oplus TM \to M$ over $\pi: E \to M$ and we can see that

$$X \in \Gamma E$$
, $U \in \mathcal{L} M$ $h^{\#}(X + U) = IX + \overline{U}$

(for definition of $h^{\#}$ see [3]). Vector fields of the form

IX and \overline{U} generate the $C^{\infty}(E)$ - module $\not\succeq E[3]$.

Now, let E be a semi-Riemannian vector bundle, and M be a semi-Riemannian manifold. Then we can naturally make $E \otimes TM$ into a semi-Riemannian vector bundle and by using the map h, we can define a semi-Riemannian metric <> on E as follows:

$$\hat{u}, \hat{v} \in T_{\xi}E \quad <\hat{u}, \hat{v}> = < k(\hat{u}), k(\hat{v})>_{E} + < d\pi(\hat{u}), d\pi(\hat{v})>_{M}$$

Thus E becomes a semi-Riemannian manifold. At each point $\xi \in E$, the horizontal space \mathcal{H}_{ξ} and the vertical space $(vE)_{\xi}$ are orthogonal to each other, and the inner product on \mathcal{H}_{ξ} and $(vE)_{\xi}$ are the same as the inner products on $T_{\pi(\xi)}$ M and $E_{\pi(\xi)}$ under the isomorphism $d\pi: \mathcal{H}_{\xi} \to T_{\pi(\xi)} M$ and $k: (vE)_{\xi} \to E_{\pi(\xi)}$, respectively. So scalar products of horizontal and vertical vector fields of E are zero.

Let C be a set and G be a semi-Riemannian vector bundle. Assume that f, g: $C \to G$ are functions such that for each $x \in C$, f(x) and g(x) are in the same fiber. Then < f, g > denotes the function from C to IR given by

$$\forall x \in C$$
 $\langle f, g \rangle (x) = \langle f(x), g(x) \rangle$

Now, let F_1 , $F_2: E \to E$ and A_1 , $A_2: E \to TM$ be strong bundle maps (not necessarily linear) clearly

$$<\tilde{F}_{1}, \tilde{F}_{2}>_{TE} = < F_{1}, F_{2}>_{E} < \overline{A}_{1}, \overline{A}_{2}>_{TE} = < A_{1}, A_{2}>_{M}$$

From now on we assume that the metric of the vector bundle is parallel with respect to ∇ , namely for every X, $Y \in \Gamma$ E and $U \in \mathcal{X}$ M we have

$$U < X, Y > = < \nabla_{U} X, Y > + < X, \nabla_{U} Y >$$

The Levi-Civita Connection of E

To compute the Levi-Civita connection of E, we need derivations of some functions on E along some fundamental vector fields.

Proposition 2. Let $X, Y \in \Gamma E, U, V \in \mathcal{X}$ M and $F: E \to E, A: E \to TM$ be linear strong bundle maps. Then

$$\overline{V} < F, X \circ \pi > = < \nabla_V F, X \circ \pi > + < F, (\nabla_V X) \circ \pi >$$
 (1)

$$IY < F, X \circ \pi > = < F \circ Y, X > \circ \pi$$
 (2)

$$\overline{V} < A$$
, $U \circ \pi > = < \nabla_V A$, $U \circ \pi > + < A$, $(\nabla_V^M U) \circ \pi > (3)$

 $IY < A, U \circ \pi > = < A \circ Y, U > \circ \pi \tag{4}$

Proof. The proof of (1) (resp. (2)) is the same as the proof of (3) (resp. (4)). So we prove (1) and (2). By definition

$$(IY)_{\xi} = I_{\xi} Y_{\pi(\xi)} = \frac{d}{dt}|_{t=0} (\xi + tY_{\pi(\xi)})$$

so for $\pi(\xi) = p$

$$(IY < F, X \circ \pi >) \xi = (IY) \xi < F, X \circ \pi >$$

$$= \frac{d}{dt}|_{t=0} < F, X \circ \pi > (\xi + tY_p)$$

$$= \frac{d}{dt}|_{t=0} < F(\xi + tY_p), X_p >$$

$$= \frac{d}{dt}|_{t=0} (< F(\xi), X_p > + t < F(Y_p), X_p >)$$

$$= < F(Y_p), X_p > = < F \circ Y, X > \circ \pi(\xi)$$

This proves (2). Now if $V_p = 0$, then concerning (1) there is nothing to prove. So let $V_p \neq 0$, and suppose that $\alpha:] -\varepsilon$, $\varepsilon[\to M$ is a curve such that $\alpha'(0) = V_p$. Set

 $\bar{\alpha}(t) = (\mathrm{IP}_{\alpha}\xi)(t)$. So $\bar{\alpha}'(0) = (\bar{V})_{\xi}$. We can find a section of E say Y, such that for small t, $Y_{a(t)} = \bar{\alpha}(t)$, so $\nabla_{V_p}Y = 0$. Now we are ready to prove (1). From the above we have

 $(\overline{V} < F, X \circ \pi >)(\xi) = \overline{V}_{\xi} < F, X \circ \pi >$ $= \frac{d}{dt}|_{t=0} < F, X \circ \pi > (\overline{\alpha}(t))$ $= \frac{d}{dt}|_{t=0} < F(\overline{\alpha}(t)), X_{\alpha(t)} > = \frac{d}{dt}|_{t=0} < F(Y_{\alpha(t)}), X_{\alpha(t)} >$ $= \frac{d}{dt}|_{t=0} < F \circ Y, X > (\alpha(t)) = \alpha'(0) < F \circ Y, X >$ $= V_p < F \circ Y, X >$ $= < \nabla_{V_p}(F \circ Y), X_p > + < (F \circ Y)(p), \nabla_{V_p} X >$ $= < (\nabla_{V_p} F)(Y_p) + F(\nabla_{V_p} Y), X_p > + < F(Y_p), \nabla_{V_p} X >$ $= < (\nabla_{V_p} F)(\xi), X_p > + < F(\xi), \nabla_{V_p} X >$ $= < \nabla_{V_p} F \circ Y, X \circ \pi > (\xi) + < F, (\nabla_{V_p} X) \circ \pi > (\xi) . \bullet$

Let $\diamondsuit(E)$ be the vector bundle over M, whose fiber at each point $p \in M$ is $\diamondsuit(E_p)$ and let $L(\wedge^2TM, \diamondsuit(E))$ be the vector bundle over M, whose fiber at each point $p \in M$ is $L(\wedge^2T_pM, \diamondsuit(E_p))$ (space of linear maps between these vector spaces). Then R(the curvature tensor of ∇) is a section of $L(\wedge^2TM, \diamondsuit(E))$. As mentioned above, $\diamondsuit(E)$ and $\diamondsuit(TM)$ are naturally isomorphic to \wedge^2E and \wedge^2TM . So we use them interchangeably, and assume that

$$R \in \Gamma L(\wedge^2 TM, \wedge^2 E).$$

Then

$$R^* \in \Gamma L(\wedge^2 E, \wedge^2 TM).$$

or

$$R^* \in \Gamma L(\wedge^2 E, \diamondsuit(TM)).$$

which is defined explicitly and uniquely by the following formula

$$X, Y \in \Gamma E, U, V \in \mathcal{X}M$$
 $\langle R(U, V)(X), Y \rangle_E$
= $\langle R^*(X, Y)(U), V \rangle_M$.

For example if E = TM, and $\nabla = \nabla^M$ (the Levi-Civita connection of M), then $R^* = R$. In other words, R is symmetric with respect to the inner product of $\wedge^2 TM$.

Theorem 3. Let $\overline{\nabla}$ denote the Levi-Civita

connection of E. If $F: E \to E$ and $A: E \to TM$ are linear strong bundle maps and $X, Y \in \Gamma E, U, V \in \mathcal{X} M$, then

$$\overline{\nabla}_{IX}IY=0\tag{5}$$

$$\overline{\nabla}_{U} \, \overline{V} = \overline{\nabla_{U}^{M} V} - \frac{1}{2} R \left(\widetilde{U}, V \right) \tag{6}$$

$$\overline{\nabla}_{IX}\overline{U} = \frac{1}{2}\overline{R^*(.,X)(U)}$$
 (7)

$$\bar{\nabla}_{IX}\tilde{F} = IF \circ X \tag{8}$$

$$\overline{\nabla}_{IX}\overline{A} = \overline{A \circ X} + \frac{1}{2}\overline{R^*(.,X)(A(.))}$$
 (9)

$$\overline{\nabla}_{U}\widetilde{F} = \overline{\nabla}_{U}F + \frac{1}{2}\overline{R^{*}(.,F(.))(U)}$$
 (10)

$$\overline{\nabla}_{\overline{U}}\overline{A} = \overline{\nabla_{U}A} - \frac{1}{2}R(U, \overline{A}(.))(.)$$
 (11)

Proof. The theorem is a consequence of the identities in section 2 and this section and the following two assertions:

1) The Levi-Civita connection of a semi-Riemannian manifold N is uniquely determined by the following formula [9]. For $U, V, W \in \mathcal{X}N$

$$2 < \nabla_U V, W > = U < V, W > + V < W, U > -W < U, V > \\ + < [U, V], W > - < [V, W], U > + < [W, U], V >$$

2) Two vector fields $\hat{U},\hat{V}\in \varkappa$ E are equal if and only if for each $Z\in \Gamma$ E and $W\in \varkappa$ M

$$\langle U, \overline{W} \rangle = \langle \hat{V}, \overline{W} \rangle, \langle \hat{U}, IZ \rangle = \langle \hat{V}, IZ \rangle$$

We prove only the assertions (10) and (11). Let us prove (10).

$$2 < \overline{\nabla}_{\overline{U}} \widetilde{F}, IZ > = \overline{U} < \widetilde{F}, IZ > + \widetilde{F} < IZ, \overline{U} > - IZ < \overline{U}, \widetilde{F} >$$

$$+ < [\overline{U}, \widetilde{F}], IZ > - < [\widetilde{F}, IZ], \overline{U} > + < [IZ, \overline{U}], \widetilde{F} >$$

$$= \overline{U} < F, Zo \pi > + < \widetilde{\nabla}_{U} F, IZ > - < - I(FoZ),$$

$$\begin{split} & \overline{U} > + \langle -I \nabla_{U} Z, \widetilde{F} > \\ & = \langle \nabla_{U} F, Zo \pi \rangle + \langle F, (\nabla_{U} Z) o \pi \rangle + \langle \nabla_{U} F, \\ & Zo \pi \rangle - \langle (\nabla_{U} Z) o \pi, F \rangle \\ & = 2 \langle \nabla_{U} F, Zo \pi \rangle = 2 \langle \overline{\nabla_{U} F} + \frac{1}{2} \overline{R^* (., F(.))(U)}, IZ \rangle \\ & 2 \langle \overline{\nabla_{U}} \widetilde{F}, \overline{W} \rangle = \overline{U} \langle \widetilde{F}, \overline{W} \rangle + \widetilde{F} \langle \overline{W}, \overline{U} \rangle - \overline{W} \langle \overline{U}, \widetilde{F} \rangle \\ & + \langle [\overline{U}, \widetilde{F}], \overline{W} \rangle - \langle [\widetilde{F}, \overline{W}], \overline{U} \rangle + \langle [\overline{W}, \overline{U}], \widetilde{F} \rangle \\ & = \widetilde{F} \langle W, U \rangle o \pi + \langle \overline{\nabla_{U} F}, \overline{W} \rangle - \langle -\overline{\nabla_{W} F}, \overline{U} \rangle \\ & + \langle [\overline{W}, \overline{U}] - R(\overline{W}, U), \widetilde{F} \rangle \\ & = d\pi(\widetilde{F}) \langle W, U \rangle - \langle R(\overline{W}, U), \widetilde{F} \rangle \\ & = -\langle R(W, U), F \rangle = \langle R(U, W)(.), F(.) \rangle \\ & = \langle R^*(., F(.))(U), W \rangle = 2 \langle \overline{\nabla_{U} F} + \frac{1}{2} \overline{R^* (., F(.))(U)}, \overline{W} \rangle \end{split}$$

Now we prove (11).

$$\langle \overline{\nabla}_{\overline{U}} \overline{A}, IZ \rangle = \overline{U} \langle \overline{A}, IZ \rangle + \overline{A} \langle IZ, \overline{U} \rangle - IZ \langle \overline{U}, \overline{A} \rangle$$

$$+ \langle [\overline{U}, \overline{A}], IZ \rangle - \langle [\overline{A}, IZ], \overline{U} \rangle + \langle [IZ, \overline{U}], \overline{A} \rangle$$

$$= -IZ \langle \overline{U} \circ \pi, A \rangle + \langle \overline{L}_{U} \overline{A} - R(U, \overline{A}(.))(.),$$

$$IZ \rangle - \langle -\overline{A} \circ \overline{Z} + \overline{\nabla}_{A(.)} Z, \overline{U} \rangle$$

$$+ \langle -I \nabla_{U} Z, \overline{A} \rangle = -\langle U, A \circ Z \rangle - \langle R(U, \overline{A}(.))(.), IZ \rangle$$

$$+ \langle A \circ Z, U \rangle = 2 \langle \overline{\nabla}_{U} \overline{A} - \frac{1}{2} R(U, \overline{A}(.))(.), IZ \rangle$$

To complete the proof, fix $\xi \in E_p$ and suppose X is a section of E such that $X_p = \xi$ and for each $u \in T_p M$, $\nabla_u X = 0$. As mentioned before for each $U \notin \mathcal{X} M$ we have $[\overline{U}, \overline{A}]_{\xi} = [\overline{U}, \overline{A} \circ \overline{X}]_{\xi}$. By a direct computation we can see that for each U, $V \in \mathcal{X} M$

$$\overline{U}_{\xi} < A$$
, Vo $\pi > = U_p < A$ o X, V>.

Now

$$2<\bar{\nabla}_{\bar{U}}\bar{A},\bar{W}>(\xi)=\bar{U}_{\xi}<\bar{A},\bar{W}>+\bar{A}_{\xi}<\bar{W},\bar{U}>-\bar{W}_{\xi}<\bar{U},\bar{A}>$$

$$+ \langle [\overline{U}, \overline{A}], \overline{W} \rangle (\xi) - \langle [\overline{A}, \overline{W}], \overline{U} \rangle (\xi) + \langle [\overline{W}, \overline{U}], \overline{A} \rangle (\xi)$$

$$= \overline{U}_{\xi} \langle A, W \circ \pi \rangle + \overline{A}_{\xi} \langle W, U \rangle \circ \pi - \overline{W}_{\xi} \langle U \circ \pi, A \rangle$$

$$+ \langle [\overline{U}, \overline{A} \circ X], \overline{W} \rangle (\xi) - \langle [\overline{A} \circ X, \overline{W}], \overline{U} \rangle (\xi)$$

$$+ \langle [\overline{W}, \overline{U}], \overline{A} \rangle (\xi)$$

$$= U_{p} \langle A \circ X, W \rangle + (A \circ X)_{p} \langle W, U \rangle - W_{p} \langle U, A \circ X \rangle$$

$$+ \langle [U, A \circ X], W \rangle (p) - \langle [A \circ X, W],$$

$$U \rangle (p) + \langle [W, U], A \circ X \rangle (p)$$

$$= 2 \langle \overline{V}_{U}^{M}(A \circ X), W \rangle (p) = 2 \langle (\overline{V}_{U} A)(X) + A(\overline{V}_{U}X), W \rangle (p)$$

$$= 2 \langle \overline{V}_{U}A, \overline{W} \rangle (\xi) = 2 \langle \overline{V}_{U}A - \frac{1}{2}R(U, \overline{A}(.))(.), \overline{W} \rangle (\xi) .$$

Geodesics of E

We know that for each $\xi \in E_p$ and $0 \in T_\xi E$ there exists a unique geodesic $\gamma:]-\varepsilon, \varepsilon[\to E]$ such that $\gamma(0)=\xi$ and $\gamma'(0)=\hat{v}$. To determine it, first suppose that \hat{v} is vertical. So $\hat{v}=I_\xi\eta$, for some $\eta\in E_p$. Let γ be the curve defined by $\gamma(t)=\xi+t\eta$ which is entirely in the fiber E_p . Trivially, $\gamma(0)=\xi$ and $\gamma'(0)=I_\xi\eta=\hat{v}$

Now choose $X \in \Gamma E$ in such a way that $X_p = \eta$, so $\gamma'(t) = (IX)_{\gamma(t)}$, thus

$$\overline{\nabla}_{\gamma(t)} \gamma' = (\overline{\nabla}_{IX} IX)_{\gamma(t)} = 0$$

Therefore, γ is the desired geodesic.

Clearly, the fibers of E are semi-Riemannian submanifolds of E and the restriction of the metric of E to them is their original metrics. By the above result, they are geodesically complete.

Now suppose that \hat{v} is not vertical and γ is the desired geodesic. Thus $\gamma'(t)$ is never vertical. Set $\alpha = \pi$ o γ . α is a curve in M, and $\alpha'(t) = d\pi(\gamma'(t)) \neq 0$. Consequently we can choose $U \in \mathcal{X}M$ such that for small t, $U_{\alpha(t)} = \alpha'(t)$. We can also choose $X \in \Gamma E$ in such a way that for small t, $X_{\alpha(t)} = \gamma(t)$. To compute $\overline{\nabla}_{\gamma} \gamma'$, we find a suitable vector field on E for which γ is an integral curve for small values of t. Clearly we have

$$d\pi(\gamma'(t)) = \alpha'(t) = U_{\alpha(t)}$$

and

$$k(\gamma'(t)) = k((X \circ \alpha)'(t)) = k(d X(\alpha'(t)))$$
$$= \nabla_{\alpha'(b)} X = (\nabla_U X)_{\alpha(b)}$$

Therefore, if we set $Y = \nabla_U X$, then $\overline{U} + IY$ is the suitable vector field.

Set, $v = d\pi(\hat{v})$, $\eta = k(\hat{v})$. So $\alpha'(0) = U_p = v$, $Y_p = \eta$, $\alpha(0) = p$. Since γ is a geodesic we have

$$0 = \overline{\nabla}_{\gamma'(t)} \gamma' = (\overline{\nabla}_{\overline{U}+IY} (\overline{U}+IY))(\gamma(t))$$
$$= (\overline{\nabla}_{\overline{U}} \overline{U} + \overline{\nabla}_{\overline{U}} IY + \overline{\nabla}_{IY} \overline{U} + \overline{\nabla}_{IY} IY)(\gamma(t))$$

$$= (\overline{\nabla_U^M} - \tfrac{1}{2} R\left(\widetilde{U}, U\right) + \overline{R^*(., Y)(U)} + I \nabla_U Y) \left(\gamma(t)\right)$$

The above relations imply the following

$$(\nabla_U^M U)(\alpha(t)) + R^* (\gamma(t), Y_{\alpha(t)})(U_{\alpha(t)}) = 0 \quad (1)$$
$$(\nabla_U Y)(\alpha(t)) = 0 \quad (2)$$

Now, recall that for a differentiable curve $h: I \to E_p$, and $\alpha: I \to M$ with $\alpha(0) = p$, we can define a section of E along α as follows:

$$t \in I$$
 $X(t) = (IP_{\alpha}h(t))(t)$

The covariant derivative of X, along α' is as follows:

$$\nabla_{\alpha'(t)}X = (\mathrm{IP}_{\alpha}h'(t))(t)$$

By repeating this formula for second derivative we have

$$\nabla_{\alpha'(t)} \nabla_{\alpha'} X = (\mathrm{IP}_{\alpha} h''(t))(t)$$

In the special case of our problem, we can assume that $X_{\alpha(t)} = (\mathrm{IP}_{\alpha}h(t))(t)$, for some $h: I \to E_p$

$$(\mathrm{IP}_{\alpha}h''(t))(t) = \nabla_{\alpha'(t)}(\nabla_{\alpha'}X) = \nabla_{\alpha'(t)}Y = (\nabla_{U}Y)(\alpha(t)) = 0$$

Thus, h'' = 0. But

$$h(0) = (IP_{\alpha}h(0))(0) = X_{\alpha(0)} = \gamma(0) = \xi$$

and

$$h'(0) = (\mathrm{IP}_\alpha h'(0))(0) = \nabla_{\alpha'(0)} \, X = Y_{\alpha(0)} = Y_p = \eta.$$

So $h(t) = \xi + t\eta$. Therefore, the geodesic γ is of the following form

$$\gamma(t) = (\mathrm{IP}_\alpha(\xi + t\eta))(t)$$

and α is a curve in M for which we have

$$\nabla_{\alpha'(t)}\alpha' + R^*(\gamma(t), Y_{\alpha(t)})(\alpha'(t)) = 0$$

From this equality we have

$$\nabla_{\alpha'(t)} \alpha' + R^*((\mathrm{IP}_\alpha(\xi + t\eta))(t) , (\mathrm{IP}_\alpha \eta)(t)) (\alpha'(t)) = 0$$

or

$$\nabla_{\alpha'(t)}\alpha' + R^*((\mathrm{IP}_{\alpha}\xi)(t), (\mathrm{IP}_{\alpha}\eta)(t))(\alpha'(t)) = 0$$
 (3)

So, α is a solution of the equation (3), with initial condition, $\alpha'(0) = v$. In some special cases, the solutions of (3) can easily be found. For example, if ∇ is flat (R = 0), then the solutions of (3) are geodesics of M. If \hat{v} is horizontal $(\eta = 0)$, then α is a geodesic of M. Thus, geodesics of E with horizontal tangent vector (at some point), are obtained by parallel transport of some points of E along some geodesics of M.

Curvature Tensor of E

Theorem 4. Let \overline{R} and R^M denote the curvature tensors of $\overline{\nabla}$ and ∇^M , respectively. Assume that $X, Y, Z \in \Gamma E$ and $U, V, W \in \mathcal{X} M$. Then

$$\overline{R}(IX , IY)(IZ) = 0 \tag{1}$$

$$\overline{R}(\overline{U}, \cline{U})(IY) = -\frac{1}{2} [\overline{R^*(X, Y)(U)} + \frac{1}{2} \overline{R^*(., X)(R^*(., Y))(U)}]$$
(2)

$$\overline{R}(IX,IY)(\overline{U}) = \overline{R^*(X,Y)(U)} + \frac{1}{4} [\overline{R^*(.,X)(R^*(.,Y)(U))} - \overline{R^*(.,Y)(R^*(.,X)(U))}]$$
(3)

$$\overline{R}(\overline{U}, IX)(\overline{V}) = \frac{1}{2}I(R(U, V)(X)) - \frac{1}{4}R(U, R^*(\widetilde{., X})(V))(.) + \frac{1}{2}(\overline{\nabla_U R^*})(., X)(V)$$

$$(4)$$

$$\overline{R}(\overline{U}, \overline{V})(IX) = I(R(U, V)(X)) - \frac{1}{2} \overline{(\nabla_{V} R^{*})(., X)(U)} + \frac{1}{2} \overline{(\nabla_{U} R^{*})(., X)(V)} - \frac{1}{4} R(U, R^{*}(., X)(V))(.)$$

$$+\frac{1}{4}R\left(V,R^{*}\left(\widetilde{.},X\right)(U)\right)(.)\tag{5}$$

$$\overline{R}(\overline{U}, \overline{V})(\overline{W}) = \overline{R^{M}(U, V)(W)} + \frac{1}{2}(\nabla_{w}R)(U, V) + \frac{1}{2}\overline{R^{*}(., R(U, V)(.))(W)} - \frac{1}{4}\overline{R^{*}(., R(V, W)(.))(U)} + \frac{1}{4}\overline{R^{*}(., R(U, W)(.))(V)}$$
(6)

Proof. The proof is by direct computation and all these computations are short except (6) which is lengthy. We compute the relation (4).

$$\begin{split} & \overline{R}(\overline{U},IX)(\overline{V}) = \overline{\nabla}_{\overline{U}} \, \overline{\nabla}_{IX} \overline{V} - \overline{\nabla}_{IX} \overline{\nabla}_{\overline{U}} \, \overline{V} - \overline{\nabla}_{[\overline{U},IX]} \overline{V} \\ & = \overline{\nabla}_{\overline{U}} \left(\frac{1}{2} \overline{R^*(.,X)(V)} \right) - \overline{\nabla}_{IX} (\overline{\nabla_{UV}} - \frac{1}{2} R(\overline{U},V)) - \overline{\nabla}_{I\nabla_{U}X} \overline{V} \\ & = \frac{1}{2} \overline{\nabla_{U}} (R^*(.,X)(V)) - \frac{1}{4} R(U,R^*(\widetilde{.,X})(V))(.) \\ & - \frac{1}{2} \overline{R^*(.,X)(\nabla_{U}V)} + \frac{1}{2} I(R(U,V)(X)) \\ & - \frac{1}{2} \overline{R^*(.,\nabla_{U}X)(V)} = \frac{1}{2} I(R(U,V)(X)) \\ & - \frac{1}{4} R(U,R^*(\widetilde{.,X})(V))(.) + \frac{1}{2} (\overline{\nabla_{U}R^*(.,X)(V)} + \overline{V}) \end{split}$$

Proposition 5. Let the metric of M be positive or negative definite. Then $\nabla R = 0$ if and only if R = 0 and $\nabla R^M = 0$.

Proof. First suppose R=0 and $\nabla R^M=0$ (this part of the proposition needs no special assumption on the metric of M). By using formulas (1)-(6) and merely the assumption R=0, we find that when at least one of the vector fields \hat{X}, \hat{Y} and \hat{Z} is vertical then $\hat{R}(\hat{X}, \hat{Y})(\hat{Z})$ is zero. Now let $U, V, W \in \mathcal{H}(M)$. Then

$$\overline{R}(\overline{U},\overline{V})(\overline{W}) = \overline{R^M(U,V)(W)}.$$

To prove that $\nabla \vec{R} = 0$, we check all possible cases. For example

$$(\vec{\nabla}_{IX}\vec{R})(IY_{1},IY_{2})(IY_{3}) = \vec{\nabla}_{IX}(\vec{R}(IY_{1},IY_{2})(IY_{3}))$$

$$-\vec{R}(\vec{\nabla}_{IX}IY_{1},IY_{2})(IY_{3}) - \vec{R}(IY_{1},\vec{\nabla}_{IX}IY_{2})(IY_{3})$$

$$-\vec{R}(IY_{1},IY_{2})(\vec{\nabla}_{IX}IY_{3}) = 0$$

The proof of the assertion in other cases is in the same way. In computation, there appear expressions which involve values of R or R^* which are zero. The only case for which we use $\nabla R^M = 0$ is the following

$$(\nabla \bar{v}_{\bar{U}} R)(\bar{V}_{1}, \bar{V}_{2})(\bar{V}_{3}) = \nabla \bar{v}_{\bar{U}}(R(\bar{V}_{1}, \bar{V}_{2})(\bar{V}_{3})) - R(\nabla \bar{v}_{\bar{U}} \bar{V}_{1}, \bar{V}_{2})(\bar{V}_{3})$$

$$- R(\bar{V}_{1}, \nabla \bar{v}_{\bar{U}} \bar{V}_{2})(\bar{V}_{3}) - R(\bar{V}_{1}, \bar{V}_{2})(\nabla \bar{v}_{\bar{U}} \bar{V}_{3}) = \nabla \bar{v}_{\bar{U}} R^{M}(V_{1}, V_{2})(V_{3})$$

$$- R(\bar{V}_{U} V_{1}, \bar{V}_{2})(\bar{V}_{3}) - R(\bar{V}_{1}, \nabla \bar{v}_{\bar{U}} \bar{V}_{2})(\bar{V}_{3}) - R(\bar{V}_{1}, \bar{V}_{2})(\nabla \bar{v}_{\bar{U}} \bar{V}_{3}) =$$

$$\nabla v_{\bar{U}} R^{M}(V_{1}, V_{2})(V_{3}) - R^{M}(\nabla v_{1}, V_{2})(V_{3}) - R^{M}(V_{1}, \nabla v_{2})(\bar{V}_{3})$$

$$- R^{M}(V_{1}, V_{2})(\nabla v_{3}) = (\nabla v_{2} R^{M})(V_{1}, V_{2})(\bar{V}_{3}) = 0$$

Now assume that $\nabla R = 0$. Let $X, Y, Z \in \Gamma E$ and $U \in \mathcal{X} M$. Then

$$0 = (\nabla \bar{U}R)(IX, IY)(IZ) = \nabla \bar{U}(R(IX, IY)(IZ))$$

$$-\bar{R}(\nabla \bar{U}IX, IY)(IZ) - \bar{R}(IX, \nabla \bar{U}IY)(IZ) - \bar{R}(IX, IY)$$

$$(\nabla \bar{U}IZ) = \bar{R}(IY, \nabla \bar{U}IX)(IZ) - \bar{R}(IX, \nabla \bar{U}IY)(IZ)$$

$$-\bar{R}(IX, \nabla \bar{U}IZ)(IY) + \bar{R}(IY, \nabla \bar{U}IZ)(IX)$$

All the terms in the above expression are in the same form. We compute one of them.

$$\overline{R}(IY, \overline{\nabla}_{\overline{U}}IX)(IZ) = \overline{R}(IY, I\nabla_{U}X + \frac{1}{2}\overline{R^{*}(., X)(U)})(IZ)$$

$$= \overline{R}(IY, \frac{1}{2}\overline{R^{*}(., X)(U)})(IZ) = \frac{1}{4}[\overline{R^{*}(Y, Z)}(R^{*}(., X)(U))$$

$$+ \frac{1}{2}\overline{R^{*}(., Y)(R^{*}(., Z)(R^{*}(., X)(U)))}]$$

So by substitution, we obtain

$$0 = R^*(Y,Z) \circ R^*(.,X)(U) + \frac{1}{2}R^*(.,Y) \circ R^*(.,Z)$$

$$\circ R^*(.,X)(U) - R^*(X,Z) \circ R^*(.,Y)(U) - \frac{1}{2}R^*(.,X)$$

$$\circ R^*(.,Z) \circ R^*(.,Y)(U) - R^*(X,Y) \circ R^*(.,Z)(U)$$

$$-\frac{1}{2}R^*(.,X) \circ R^*(.,Y) \circ R^*(.,Z)(U) + R^*(Y,X)$$

$$\circ R^*(.,Z)(U) + \frac{1}{2}R^*(.,Y) \circ R^*(.,X) \circ R^*(.,Z)(U)$$

In putting X and Z in turn in place of the dot in the above expression we obtain

$$-R*(X,Z) \circ R*(X,Y)(U) -2R*(X,Y) \circ R*(X,Z)(U) = 0$$
 (7)

$$R^*(Y,Z) \circ R^*(Z,X)(U) - R^*(X,Z) \circ R^*(Z,Y)(U) = 0$$
 (8)

Now interchange X and Z in (8) and sum the resulting expression with (7). From this and the fact that U is arbitrary, we obtain

$$R*(X, Y) \circ R*(X, Z) = 0$$

Now, set Y = Z, and $T = R^*(X, Y)$. Clearly, T is an antisymmetric map for which $T^2 = 0$. But such an antisymmetric (or symmetric) map is zero, because

$$0 = \langle T^2(v), v \rangle = \pm \langle T(v), T(v) \rangle = \pm ||T(v)||^2 \Rightarrow T(v) = 0$$

Consequently, $R^* = 0$ and so R = 0. Now by the computation in the first part of the proposition we have

$$0 = (\overline{\nabla_{U}R})(\overline{V_1}, \overline{V_2})(\overline{V_3}) = (\overline{\nabla_{U}R}^{M})(\overline{V_1}, \overline{V_2})(\overline{V_3}) \Rightarrow \nabla R^{M} = 0 \bullet$$

Sectional, Ricci, and Scalar Curvatures of E

With \overline{R} in hand, we can easily compute other curvatures of E. In general, if σ is a non-degenerate plane of $T_{\xi}E$, for some $\xi \in E$, and $\{\hat{v}, \hat{u}\}$ is a base of σ , then the sectional curvature of E along σ , denoted by \overline{K}_{σ} is

$$\overline{K}_{\sigma} = \frac{\langle \overline{R} (\hat{u}, \hat{v})(\hat{v}), \hat{u} \rangle}{\langle \hat{u}, \hat{u} \rangle \langle \hat{v}, \hat{v} \rangle \langle \hat{v}, \hat{v} \rangle - \langle \hat{u}, \hat{v} \rangle^{2}}$$

(The denominator is non-zero if and only if σ is non-degenerate). To indicate that $\{\hat{u}, \hat{v}\}$ is a base of σ , we denote σ by $\sigma(\hat{u}, \hat{v})$.

Proposition 6. Let $p \in M$, u, $v \in T_pM$ and ξ , ζ , $\eta \in E_p$. Assume that

$$< u, v>=0, < \eta, \zeta>=0, |< u, u>| = |< v, v>|$$

$$= \left| \langle \eta, \eta \rangle \right| = \left| \langle \zeta, \zeta \rangle \right| = 1.$$

Let K be the sectional curvature of M. Then

$$\overline{K}_{\sigma(u\xi,v\xi)} = K_{\sigma(u,v)} - \frac{3}{4} \operatorname{sgn}(u) \operatorname{sgn}(v) \| R(u,v)(\xi) \|^2$$
 (1)

$$\overline{K}_{\sigma(\underline{u}\xi,I_{\xi}\eta)} = \frac{1}{4} \operatorname{sgn}(u) \operatorname{sgn}(\eta) \|R^*(\xi,\eta)(u)\|^2$$
 (2)

$$\overline{K}_{\sigma(I_{\mathcal{E}}\eta,I_{\mathcal{E}}\zeta)}=0 \tag{3}$$

Proof. Clearly

$$<\overline{u}_{\xi},\overline{u}_{\xi}><\overline{v}_{\xi},\overline{v}_{\xi}>-<\overline{u}_{\xi},\overline{v}_{\xi}>^{2}=sgn(u)sgn(v)$$

and

So (1) is proved. On the other hand, clearly

$$<\overline{u}\xi,\overline{u}\xi>< I_{\xi}\eta,I_{\xi}\eta>-<\overline{u}\xi,I_{\xi}\eta>^2=sgn(u)sgn(\eta)$$

Furthermore

$$\langle \overline{R}(\overline{u}_{\xi}, I_{\xi}\eta)(I_{\xi}\eta), \overline{u}_{\xi} \rangle = \langle -\frac{1}{2}(\overline{R^{*}(\eta, \eta)(u)})_{\xi}$$

$$-\frac{1}{4}(\overline{R^{*}(\xi, \eta)(R^{*}(\xi, \eta)(u))})_{\xi}, \overline{u}_{\xi} \rangle =$$

$$-\frac{1}{4}\langle R^{*}(\xi, \eta)(R^{*}(\xi, \eta)(u)), u \rangle$$

$$= \frac{1}{4}\langle R^{*}(\xi, \eta)(u), R^{*}(\xi, \eta)(u) \rangle = \frac{1}{4} ||R^{*}(\xi, \eta)(u)||^{2}$$

So (2) is proved. In the same way (3) can be proved. •

Let $\xi \in E$. Assume that $\{\hat{e}_1, ..., \hat{e}_k\}$ is an orthonormal basis for $T_{\xi}E$. Let \overline{S} (resp. \overline{r}) denote the Ricci curvature (resp. scalar curvature) of E. Then

$$\overline{S}(\hat{u}, \hat{v}) = \sum_{i=1}^{k} sgn(\hat{e}_{i}) < \overline{R}(\hat{e}_{i}, \hat{u})(\hat{v}), \hat{e}_{i} > \hat{u}, \hat{v} \in T_{\xi}E$$

$$\overline{r}_{\xi} = \sum_{i=1}^{k} sgn(\hat{e}_i) \overline{S}(\hat{e}_i, \hat{e}_i)$$

Proposition 7. Let $p \in M$, $\xi \in E_p$. Assume that $\{v_1, ..., v_n\}$ and $\{\eta_1, ..., \eta_m\}$ are orthonormal bases for T_pM and E_p , respectively. If S (resp. r) denotes Ricci curvature (resp. scalar curvature) of M, then for ζ , $\eta \in E_p$ and u, $v \in T_pM$ we have

$$\overline{S}(I_{\xi}\eta,I_{\xi}\zeta) = \frac{1}{4} \sum_{i=1}^{n} sgn(v_{i}) < R^{*}(\xi,\zeta)(v_{i}), R^{*}(\xi,\eta)(v_{i}) >$$

$$(4)$$

$$\overline{S}(\overline{u}_{\xi}, I_{\xi}\eta) = \frac{1}{2} \sum_{i=1}^{n} sgn(v_{i}) < (\nabla_{v_{i}} R^{*})(\xi, \eta)(u), v_{i} > (5)$$

$$\overline{S}(\overline{u}_{\xi}, \overline{v}_{\xi} = S(u, v) + \frac{1}{4} \sum_{j=1}^{m} sgn(\eta_{j}) < R^{*}(\xi, \eta_{j})(u),$$

 $R^*(\xi, \eta_i)(\upsilon) >$

$$-\frac{3}{4}\sum_{i=1}^{n} sgn(v_i) < R(v_i, u)(\xi), R(v_i, v)(\xi) >$$
 (6)

$$\overline{r}_{\xi} = r_{p} + \frac{1}{2} \sum_{i=1}^{n} \sum_{j=1}^{m} sgn(v_{i}) sgn(\eta_{j}) \| R^{*}(\xi, \eta_{j})(v_{i}) \|^{2}$$
$$-\frac{3}{4} \sum_{i,j=1}^{n} sgn(v_{i}) sgn(v_{j}) \| R(v_{i}, v_{j})(\xi) \|^{2}$$
(7)

The proof is by direct computation.

Proposition 8. If the metric of M is definite (positive or negative), then E is Ricci-flat if and only if R = 0 and M is Ricci flat.

Proof. Suppose R=0 and M is Ricci flat. (This part of the proposition needs no special assumption on the metric of M). Relations (4)-(6) show that E is Ricci flat. Conversely, suppose E is Ricci flat. Let $p \in M$ and ξ , $\eta \in E_p$. Assume that $\{v_1, ..., v_n\}$ is an orthonormal basis for T_pM . Then

$$0 = \overline{S}(I_{\xi}\eta, I_{\xi}\eta) = \frac{1}{4} \sum_{i=1}^{n} \pm R^{*}(\xi, \eta)(v_{i}), R^{*}(\xi, \eta)(v_{i}) >$$

$$= \pm \frac{1}{4} \sum_{i=1}^{n} \|R^{*}(\xi, \eta)(v_{i})\|^{2}$$

$$\Rightarrow R^{*}(\xi, \eta)(v_{i}) = 0$$

Since, ξ and η are arbitrary and $\{v_1,..., v_n\}$ is a basis for T_pM we have $R^* = 0$. Therefore R = 0. Now by relation (6), for arbitrary $u, v \in T_pM$ we have

$$0 = \overline{S}(u_{\xi}, v_{\xi}) = S(u, v) + 0$$

Therefore S = 0

Proposition 9. If the metric of E is an Einstein metric, then E is Ricci flat.

Proof. By the definition of Einstein metric there exist $\lambda \in \mathbb{R}$ such that for every $\hat{U}, \hat{V} \in \mathcal{X}E$,

$$\bar{S}(\hat{U},\hat{V}) = \lambda < \hat{U},\hat{V} >$$

Thus, specially for each $\xi \in E$

$$\overline{S}(I_{\xi}\xi,I_{\xi}\xi) = \lambda \langle I_{\xi}\xi,I_{\xi}\xi \rangle = \lambda \langle \xi,\xi \rangle.$$

On the other hand we have

$$\bar{S}(I_{\xi}\xi J_{\xi}\xi) = \frac{1}{4} \sum_{i=1}^{n} sgn(v_{i}) < R^{*}(\xi,\xi)(v_{i}), R^{*}(\xi,\xi)(v_{i}) > 0.$$

So, for each $\xi \in E$, $\lambda < \xi$, $\xi > = 0$. But for some ξ we have $< \xi$, $\xi > \neq 0$, so $\lambda = 0$. Therefore E is Ricci flat. •

Sphere Bundles and Pseudo-Sphere Bundles

Let (V, <>) be an inner product space. The set

$$\{v \in V \mid < v, v > = 1\}$$

is denoted by S and is called the sphere in V. Similarly the set

$$\{v \in V \mid < v, v > = -1\}$$

will be denoted by \hat{S} and we shall call it the pseudo-sphere in V. When S (resp. \hat{S}) is not empty, it is a non-degenerate submanifold of V whose dimension is one less than that of V, and its sectional curvature is 1 (resp. -1). Let E be a semi-Riemannian vector bundle, its associated sphere bundle E_S and its pseudo-sphere bundle $E_{\hat{S}}$ are defined as follows:

$$E_S = \{ \xi \in E | < \xi \, , \, \xi > = 1 \} \ , E_{\ell} = \{ \xi \in E | < \xi \, , \, \xi > = -1 \}$$

The bundle E_S (resp. $E_{\frac{1}{5}}$), if not empty, is a submanifold of E whose dimension is one less than

that of E. Let Z denote the radial vector field of E ($Z = \widetilde{1}_E$). For each $\xi \in E_S$, (resp. $\xi \in E_{\hat{S}}$), Z_{ξ} is a non-degenerate vector, and by an elementary computation we see that $T_{\xi} E_S$ (resp. $T_{\xi} E_{\hat{S}}$) is equal to Z_{ξ}^{\perp} . So E_S (resp. $E_{\hat{S}}$) is a non-degenerate submanifold of E, and E is orthogonal to it. Since E is a vertical vector field for each E is E (resp. E is a vertical vector field for

$$\mathcal{H}_{\xi} \subseteq T_{\xi}E_{S}$$
 (resp. $T_{\xi}E_{\hat{\xi}}$)

So, each horizontal vector field along E_S (resp. $E_{\hat{S}}$) is tangent to it.

Proposition 10. Let T be the Weingarten map of E_S (resp. $E_{\hat{S}}$) with respect to Z. For each $\hat{u} \in T_{\xi}E_S$ (resp. $T_{\xi}E_{\hat{\theta}}$)

$$T(\hat{u}) = -I_{\mathcal{E}}k(\hat{u})$$

Proof. Let $d\pi(\hat{u}) = u$ and $k(\hat{u}) = \eta$, so $\hat{u} = u\xi + I\xi\eta$. Now by definition of T

$$\begin{split} &T(\hat{u}) = -\bar{\nabla}_{\hat{u}}^{\wedge} Z = -\bar{\nabla}_{u\xi+Z\xi\eta}^{-} \widetilde{1}_{E} = -\bar{\nabla}_{u\xi}^{-} \widetilde{1}_{E} - \bar{\nabla}_{I\xi\eta}^{-} \widetilde{1}_{E} \\ &= -I_{\xi}(\nabla_{u} 1_{E})(\xi) - \frac{1}{2} \overline{(R^{*}(\xi,\xi)(u))} \xi - I_{\xi} 1_{E}(\eta) = -I_{\xi} \eta = -I_{\xi} k \stackrel{\wedge}{(u)} \bullet \end{split}$$

Proposition 11. If π and $\hat{\pi}$ denote second fundamental forms of E_{δ} and $E_{\hat{\delta}}$ respectively, then

$$\hat{U}, \hat{V} \in \mathcal{X} E_{S} \quad \pi(\hat{U}, \hat{V}) = -\langle k(\hat{U}), k(\hat{V}) \rangle Z$$

$$\hat{U}, \hat{V} \in \mathcal{X} E_{\hat{S}} \quad \hat{\pi}(\hat{U}, \hat{V}) = \langle k(\hat{U}), k(\hat{V}) \rangle Z$$

Proof. As mentioned in section 1, for \hat{U} , $\hat{V} \in \mathcal{X}$ E_S ,

and $\xi \in E$ we have

$$\pi(\hat{U}_{\xi}, \hat{V}_{\xi}) = \langle T(\hat{U}_{\xi}), \hat{V}_{\xi} \rangle sgn(Z_{\xi}) Z_{\xi}$$
$$= \langle -I_{\xi}k(\hat{U}_{\xi}), \hat{V}_{\xi} \rangle Z_{\xi} = \langle k(\hat{U}_{\xi}), k(\hat{V}_{\xi}) \rangle Z_{\xi}$$

For E_{\emptyset} a similar computation can be done. •

Now, we can easily compute the curvatures of E_S or E_{\S} . For example, we see that sectional curvatures of E_S and E_{\S} in the direction of the planes which have at least one horizontal vector are the same as those of E, and in the direction of the vertical planes they are constantly + 1 and -1, respectively.

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